

SELF-CONSISTENT APPROACH TO ESTIMATING LONG-TERM AND INTERANNUAL VARIABILITY WITH COMBINED SPATIAL SCALES IN HISTORICAL DATA SETS

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1. MOTIVATION

All interpolation procedures require the assumption of various a priori estimates: mean and covariances of the target fields as well as observational error covariances. All these parameters are usually being estimated from available observations. Posterior consistency of the analysis results with a priori assumptions is not guaranteed and often not tested. Schneider (2001) proposed an Expectation-Maximization based iterative procedure that allows to achieve consistency for the target field covariance estimate. Here we generalize this procedure for estimating means (climatology) too, while also relaxing his assumption of zero (or ridge-regression selected) observational error.

The practical implementation of the proposed procedure also requires the appropriate treatment of small scales, if working with space-space covariance matrix is impractical. Dealing with small scales poses a bunch of new problems, like proper specification of their covariance and also correct evaluation of their total variance, that is useful for accurate modeling of observational error.

2. NEW PROCEDURE

Consistent estimation of sliding window climatology and covariances

The OI problem, i.e. estimating the field T from a first-guess (background) solution T^0 to be the sliding window climatology T^{00} and an incomplete set of observations T^{01} is given by:

$$T = T^{00} + \epsilon^{00}, \quad \langle \epsilon^{00} \rangle = 0, \quad \langle \epsilon^{00} \epsilon^{00T} \rangle = C_0$$

$$T^{01} = T^{00} + \epsilon^{01}, \quad \langle \epsilon^{01} \rangle = 0, \quad \langle \epsilon^{01} \epsilon^{01T} \rangle = R_0$$

8. Initialization: $i = 0$. Use the available solution approaches to compute T^{00} and C_0 from T^{01} . Presumably only data for recent few decades can be used in this step.

Then apply to the entire period of historical data the iterations of the following cycle, for $i = 0, 1, 2, \dots$, until convergence (similar to Expectation-Maximization approach, e.g. Schneider 2001).

1. Given the estimates of T^{00} and C_0 , compute the OI solution, i.e. interpolated fields T^{00} and error covariance estimate P_i :

$$T^{00} = T^{00} + \epsilon^{00}, \quad \langle \epsilon^{00} \rangle = 0, \quad \langle \epsilon^{00} \epsilon^{00T} \rangle = C_0$$

$$P_i = C_0 - C_0 B^T (R + B C_0 B^T)^{-1} B C_0$$

2. Adjust climatology (smaller angle brackets denote sliding time window averaging):

$$T^{00} = T^{00} + \epsilon^{00}, \quad \langle \epsilon^{00} \rangle = 0, \quad \langle \epsilon^{00} \epsilon^{00T} \rangle = C_0$$

3. Compute new covariance estimates:

$$C_{i+1} = \left(\langle \epsilon^{00} \epsilon^{00T} \rangle - \langle \epsilon^{00} \rangle \langle \epsilon^{00} \rangle^T \right) + P_i$$

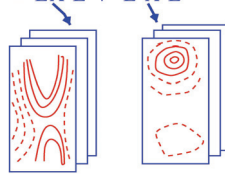
4. Increase i :

$$i = i + 1$$

and go to step 1.

APPROXIMATING COVARIANCE

$$C = E \Lambda E^T + E' \Lambda' E'^T$$



Scale separation in a field estimate

OI problem: estimating a field T from a first-guess (background) solution T^0 and an incomplete set of observations T^1 is given by:

$$T = T^0 + \epsilon^0, \quad \langle \epsilon^0 \rangle = 0, \quad \langle \epsilon^0 \epsilon^{0T} \rangle = C_0$$

$$T^1 = T^0 + \epsilon^1, \quad \langle \epsilon^1 \rangle = 0, \quad \langle \epsilon^1 \epsilon^{1T} \rangle = R_0$$

The solution to this OI problem is a minimizer $\hat{T}$ of the cost function $S[T] = (T - T^0)^T R^{-1} (T - T^0) + (T - T^1)^T C^{-1} (T - T^1)$.

$$\hat{T} = C H^T (R + H C H^T)^{-1} T^1$$

$$C = E \Lambda E^T + E' \Lambda' E'^T$$

$$\hat{T} = E \hat{\Lambda} + \hat{\Lambda}'$$

$$T^0 = H E \hat{\Lambda} + \epsilon^0, \quad \langle \epsilon^0 \rangle = 0, \quad \langle \epsilon^0 \epsilon^{0T} \rangle = H C H^T + R_0$$

$$\hat{\Lambda} = \Lambda E^T H^T (H \Lambda E^T H^T + H C H^T + R_0)^{-1} T^1$$

$$\text{Observational residual: } \Delta T^0 = T^0 - H E \hat{\Lambda}$$

$$\Delta T^0 = H \Delta \Lambda + \epsilon^0, \quad \langle \Delta T^0 \Delta T^{0T} \rangle = C^0, \quad \langle \epsilon^0 \epsilon^{0T} \rangle = R_0$$

$$\Delta T = C^0 H (H C^0 H^T + R_0)^{-1} \Delta T^0$$

3. EXAMPLE: RS SOLUTION

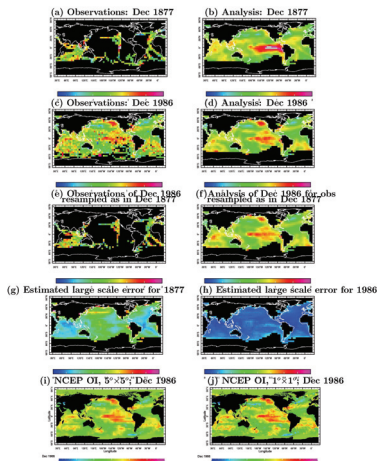


Figure 2. Available SST observations and their RS OS analysis for December 1877 (panels (a) and (b)) with verification through the experiment with 1986 data: simulated OS analysis for December 1986 using the data distribution of 1877 (panels (c) and (d)) versus the standard OS analysis for December 1986 with all available data (panels (e) and (f)). Also shown are large scale errors in the two reconstructions (panels (g) and (h)) and the NCEP OI Dec 1986 field presented in (i) 5°x5° resolution, (j) 1°x1° resolution. Units are °C.

There is significant room for improvement, as far as reconstruction of small-scale variability is concerned. We need to model it adequately

4. SMALL-SCALE VARIABILITY

